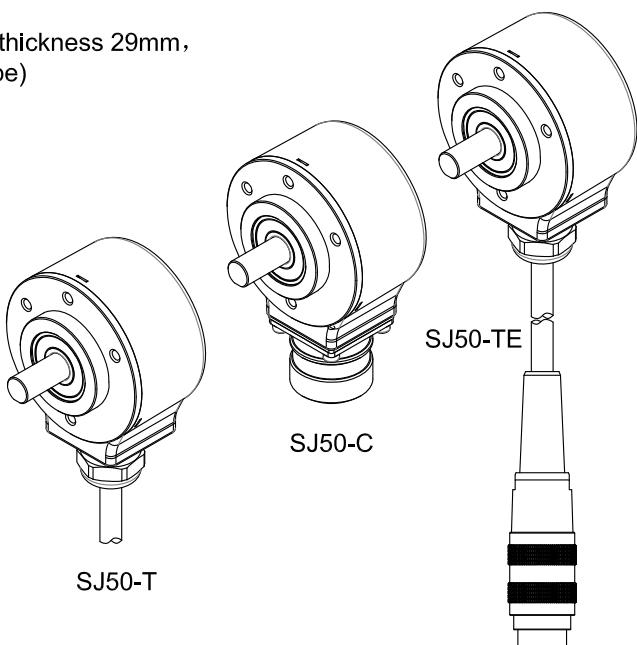


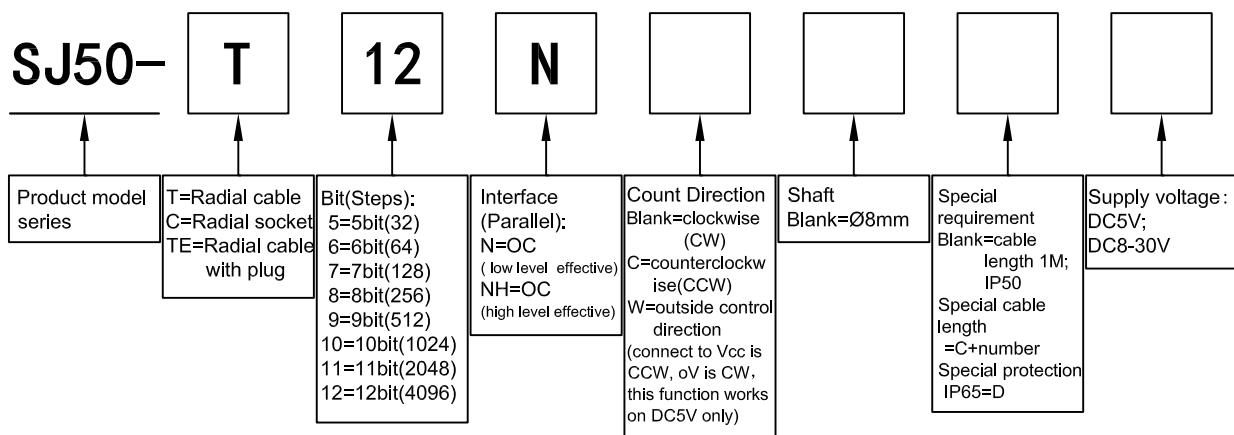
■ Absolute Type-Parallel output(Solid Shaft)

- Feature: sturdy and durable, output gray code without reading error, direction can be controlled by outside
- Application: automation control like motor, CNC, package machine, industrial assembly line, etc.
- External dimensions: external diameter Ø51mm, thickness 29mm, diameter of shaft 8mm(D type)
- Resolution: 12bit(4096 steps per turn)
- Output code: Gray code
- Supply voltage: DC5V; DC8-30V
- Protection: IP50; IP65
- Cable length: 1000mm
- Weight: about 300g



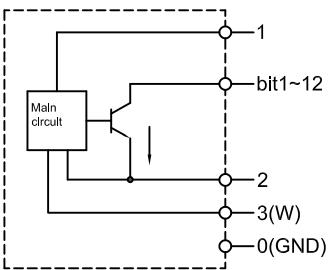
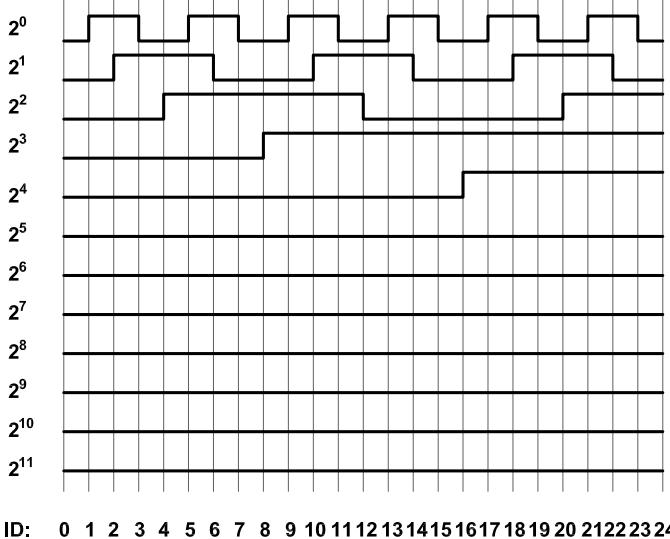
■ Model Guide

- Model form (filled required parameters in the box as following)



- If need coupling and bracket, please purchase additionally (accessory at specifications 5/5)

■ Output Mode

Interface(Parallel)	Output circuit	Output wave form
OC	 <p>Main circuit</p>	 <p>ID: 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 View from shaft end, rotate direction is clockwise(CW)</p>

■ Connection (The shielding wire is not connected to encoder)

Socket Pin No.	Resolution4096	Resolution2048	Resolution1024	Resolution 512	Resolution 256	Resolution 128	Resolution 64	Resolution 32
15=R=pink/black	bit1(2^0)	not connect	←	←	←	←	←	←
14=P=gray/black	bit2(2^1)	bit1(2^0)	not connect	←	←	←	←	←
13=O=blue/black	bit3(2^2)	bit2(2^1)	bit1(2^0)	not connect	←	←	←	←
12=N=yellow/black	bit4(2^3)	bit3(2^2)	bit2(2^1)	bit1(2^0)	not connect	←	←	←
11=M=green/black	bit5(2^4)	bit4(2^3)	bit3(2^2)	bit2(2^1)	bit1(2^0)	not connect	←	←
10=L=white/black	bit6(2^5)	bit5(2^4)	bit4(2^3)	bit3(2^2)	bit2(2^1)	bit1(2^0)	not connect	←
9=K=pink	bit7(2^6)	bit6(2^5)	bit5(2^4)	bit4(2^3)	bit3(2^2)	bit2(2^1)	bit1(2^0)	not connect
8=I=gray	bit8(2^7)	bit7(2^6)	bit6(2^5)	bit5(2^4)	bit4(2^3)	bit3(2^2)	bit2(2^1)	bit1(2^0)
7=H=blue	bit9(2^8)	bit8(2^7)	bit7(2^6)	bit6(2^5)	bit5(2^4)	bit4(2^3)	bit3(2^2)	bit2(2^1)
6=G=yellow	bit10(2^9)	bit9(2^8)	bit8(2^7)	bit7(2^6)	bit6(2^5)	bit5(2^4)	bit4(2^3)	bit3(2^2)
5=F=green	bit11(2^{10})	bit10(2^9)	bit9(2^8)	bit8(2^7)	bit7(2^6)	bit6(2^5)	bit5(2^4)	bit4(2^3)
4=E=white	bit12(2^{11})	bit11(2^{10})	bit10(2^9)	bit9(2^8)	bit8(2^7)	bit7(2^6)	bit6(2^5)	bit5(2^4)
3=D=brown	W (direction control)							
2=C=black	OV							
1=B=red	DC5V; DC8-30V							
0=A=shielding	GND							

■ Electrical Characteristics

Parameter Item	Interface (Parallel)		OC	OC		
Supply voltage	DC5V±5%; DC8V-30V±5%					
Allowable ripple	≤3%rms					
Consumption current	100mA Max					
Output code	gray code					
Precision	[360/(resolutionx4)]°					
Top response frequency	100kHz Max					
Output volume	Output current	Input	≤30mA			
	Output voltage	Output	—			
	Output voltage	"H"	—			
	Output voltage	"L"	≤0.4V			
Load voltage	≤DC30V					
Rise & Fall time	Less than 2us (Load resistance 1KΩ、cable length: 2m)					
Output level	Low level available			High level available		
Insulation strength	AC500V 60s					
Insulation resistance	10MΩ					
GND	not connect to encoder					

■ Mechanical Characteristics

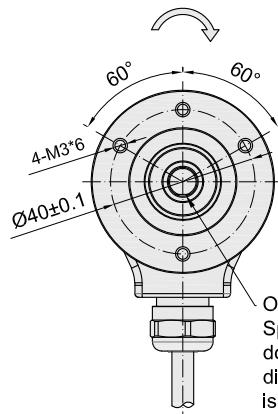
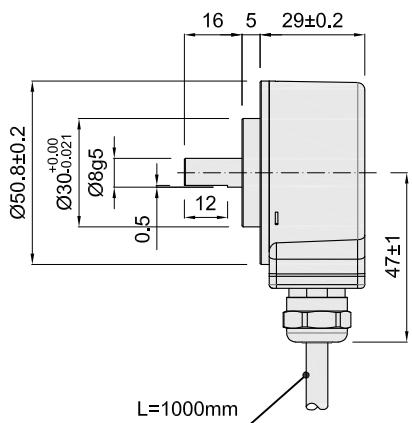
Shaft	Ø8mm(stainless steel)
Starting torque	Less than 5×10^{-3} N·m
Inertia moment	Less than 3×10^{-6} kg·m ²
Shaft load	Radial 50N; Axial 30N
Slew speed	≤3000 rpm; IP65≤2000 rpm
Bearing Life	1.5x10 ⁹ revs at rated load(10000hrs at 2500RPM)
Shell	Die cast aluminum
Weight	about 300g(with package)

■ Environmental Specifications

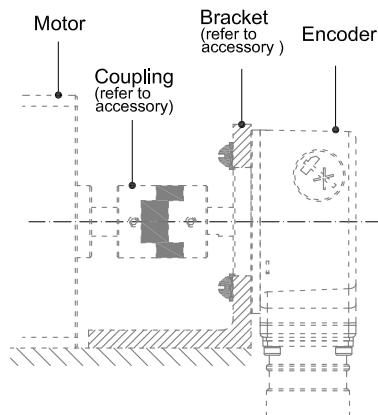
Environmental temperature	Operating: -20~+85°C(repeatable winding cable: -10°C); storage: -25~+90°C
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)
Vibration(endure)	Amplitude 0.75mm, 5~55Hz, 2h for X,Y,Z direction individually
Shock(endure)	490m/s ² , three times for X,Y,Z direction individually
Protection	IP50; IP65

■ Basic Dimensions

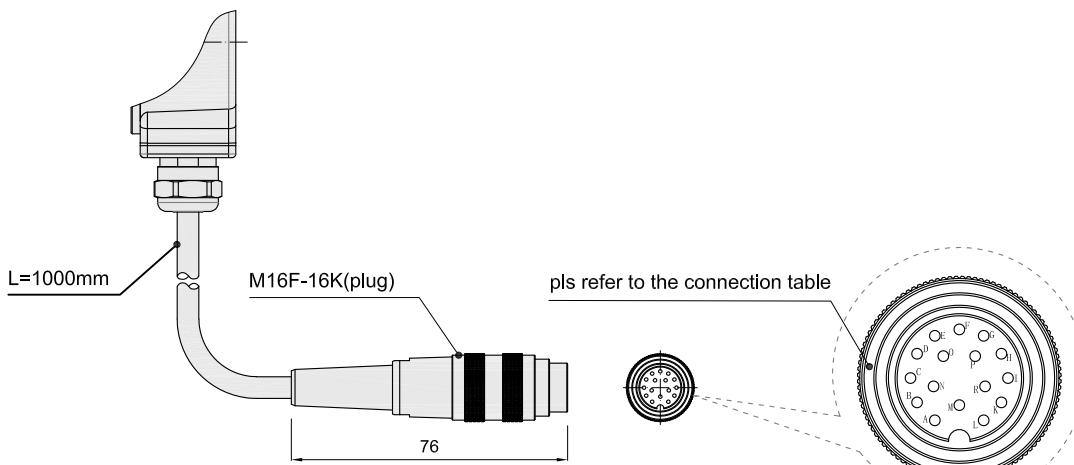
● SJ50-T



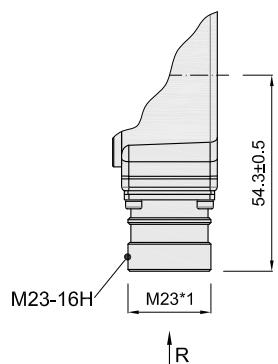
Origin location:
Spindle notching face
down to cable outlet
direction & surface hole
is the origin position



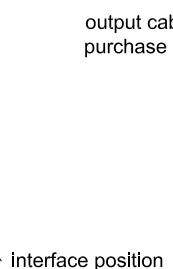
● SJ50-TE



● SJ50-C

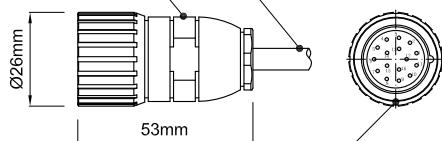


R = Radial



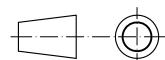
output cable offered by client or
purchase separately

M23-16A



pls refer to the connection table

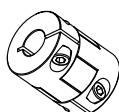
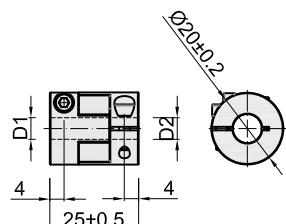
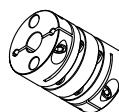
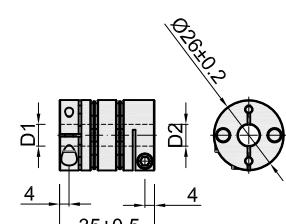
Unit: mm



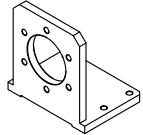
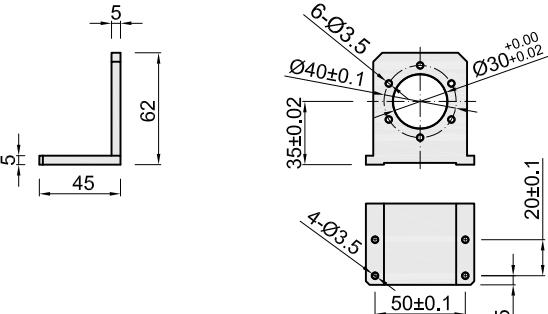
= Clockwise direction for shaft rotation

■ Accessory(Need purchase additionally)

- Coupling

M series oldham coupling (general accuracy, or choose W series for higher accuracy) 6M8 No:8700038 8M8 No:8700039 8M10 No:8700040			<table border="1"><thead><tr><th>Model</th><th>D1</th><th>D2</th></tr></thead><tbody><tr><td>6M8</td><td>$\varnothing 6^{+0.01}_{-0.03}$</td><td>$\varnothing 8^{+0.01}_{-0.03}$</td></tr><tr><td>8M8</td><td>$\varnothing 8^{+0.01}_{-0.03}$</td><td></td></tr><tr><td>8M10</td><td></td><td>$\varnothing 10^{+0.01}_{-0.03}$</td></tr></tbody></table> <p>material: aluminium alloy</p>	Model	D1	D2	6M8	$\varnothing 6^{+0.01}_{-0.03}$	$\varnothing 8^{+0.01}_{-0.03}$	8M8	$\varnothing 8^{+0.01}_{-0.03}$		8M10		$\varnothing 10^{+0.01}_{-0.03}$
Model	D1	D2													
6M8	$\varnothing 6^{+0.01}_{-0.03}$	$\varnothing 8^{+0.01}_{-0.03}$													
8M8	$\varnothing 8^{+0.01}_{-0.03}$														
8M10		$\varnothing 10^{+0.01}_{-0.03}$													
W series plate flexible coupling (high accuracy) 6W8 No:8700042 8W8 No:8700043 8W10 No:8700044			<table border="1"><thead><tr><th>Model</th><th>D1</th><th>D2</th></tr></thead><tbody><tr><td>6W8</td><td>$\varnothing 6^{+0.01}_{-0.03}$</td><td>$\varnothing 8^{+0.01}_{-0.03}$</td></tr><tr><td>8W8</td><td>$\varnothing 8^{+0.01}_{-0.03}$</td><td></td></tr><tr><td>8W10</td><td></td><td>$\varnothing 10^{+0.01}_{-0.03}$</td></tr></tbody></table> <p>material: aluminium alloy</p>	Model	D1	D2	6W8	$\varnothing 6^{+0.01}_{-0.03}$	$\varnothing 8^{+0.01}_{-0.03}$	8W8	$\varnothing 8^{+0.01}_{-0.03}$		8W10		$\varnothing 10^{+0.01}_{-0.03}$
Model	D1	D2													
6W8	$\varnothing 6^{+0.01}_{-0.03}$	$\varnothing 8^{+0.01}_{-0.03}$													
8W8	$\varnothing 8^{+0.01}_{-0.03}$														
8W10		$\varnothing 10^{+0.01}_{-0.03}$													

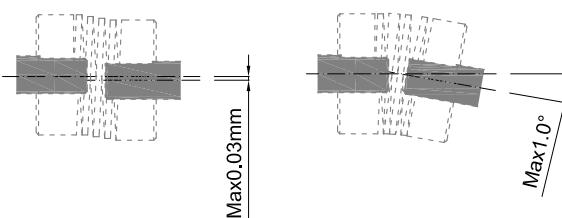
- Bracket

50L30 No:3500165		
material: aluminium alloy		

Unit: mm



- Assembling requirement



Notice : coaxiality between shaft of encoder and power shaft must be less than 0.03mm, and gradient must be less than 1.0°.

About vibration

Vibration act on encoder always cause wrong pulse , so we should pay attention to working place . More pulse per revolution , narrower groovy spacing of grating , more effect to encoder by vibration , when rev is low or stop , vibration act on shaft or main body would cause grating vibrating , so encoder might make wrong pulse .